

# Kunal Gupta

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## EDUCATION

### New York University

Bachelor of Science, Computer and Electrical Engineering, Minor in Robotics (Dean's List)

Expected June 2026

GPA: (3.93/4)

**Academic Focuses:** Deep Learning, Full Stack, Software Engineering, Embedded Systems, Genomics, Medtech

## INDUSTRY EXPERIENCE

### Boston Scientific

Firmware & Software Research and Development Intern

Summer 2025 (ongoing)

**C++, Python, Java, Embedded Systems Design**

- Designed and developed a high-performance server to connect the entire Urology R&D team (through clients, GUIs, and automation scripts) to a hardware simulation of a surgically implanted urology device
- Supports 100+ concurrent clients and coordinates 8 Arduino devices simulating pressure and temperature, all with sub 10 millisecond latency.
- Refactored 20K+ lines of legacy code into a fully tested, maintainable service layer (100% coverage); stress-tested with 40,000 requests from 40 clients to ensure safe, repeatable server validation.

### Commure

Software Engineering Intern

Summer 2024, Fall 2022

**React, CSS, Python, OpenAI API, SQL, Google Cloud Platform**

- (Summer 2024) Designed and implemented an electronic prescription platform enabling hundreds of doctors to send prescriptions to U.S. pharmacies utilizing SQL, Python, and React.
- Integrated and certified with the national e-prescription API in just four months—far exceeding the typical 2–3-year certification timeline.
- (Fall 2022) Integrated an account creation step into the company's front-end, eliminating the need for multiple contracts, forms, and calls. Reduced onboarding time by 40% resulting in higher sales efficiency.

## PUBLICATIONS

- E. Tyacke, K. Gupta, J. Patel, R. Katoch, S.F. Atashzar.**  
*From Unstable Electrode Contacts to Reliable Control: A Deep Learning Approach for HD-sEMG in Neurorobotics.*  
In *IEEE International Conference on Robotics and Automation (ICRA)*, 2024. [IEEE Link](#)
- E. Tyacke, K. Gupta, J. Patel, R. Li.**  
*IsoNet: Causal Analysis of Multimodal Transformers for Neuromuscular Gesture Classification.*  
arXiv preprint [arXiv:2506.16744](https://arxiv.org/abs/2506.16744)

## RESEARCH

### Boeke Laboratory

Bioinformatics Researcher

Jan 2024 - Present

**PyTorch, JASPAR, CRISPR, Stem Cell Culture, Molecular Biology Techniques**

- Developed a Python library leveraging generative AI to design synthetic regulatory DNA like promoters / enhancers.
- Demonstrated AI generated synthetic regulatory DNA's impact on gene expression in mouse embryonic stem cells (mESCs), advancing applications in gene regulation research.
- Optimized model to train 16x faster through distributed data parallelism and mixed precision; tailored model for wide-format DNA sequence data and small-scale feature extraction.

### Medical Robotics and Interactive Intelligent Technologies Laboratory

AI Researcher

Jan 2023 – Present

**PyTorch, TensorFlow, MATLAB, Simulink, HPC**

- Achieved the highest recorded classification accuracy (98.03%) on a benchmark EMG dataset, leveraging a novel multimodal transformer deep learning model
- Developed a deep learning model enabling prosthetic limbs to recognize and execute up to 65 distinct gestures, a significant advancement over the standard two-gesture (open/close) systems on the market.

### Dynamical Systems Laboratory

Firmware Researcher

Jan 2024 – May 2025

**Altium, KiCad, PCB Design and Assembly, Arduino**

- Developed a haptic vest enabling blind / visually impaired individuals to "see" their environment through tactile feedback, conveying the location and distance of obstacles without relying on a cane. Improved traversal speeds by 1.4x and reduced the number of collisions by 2x.
- Designed and built custom electronics using Altium and soldering; the final design ensured high contact, comfort, and washability, with concealed wiring for a fashionable and practical design.